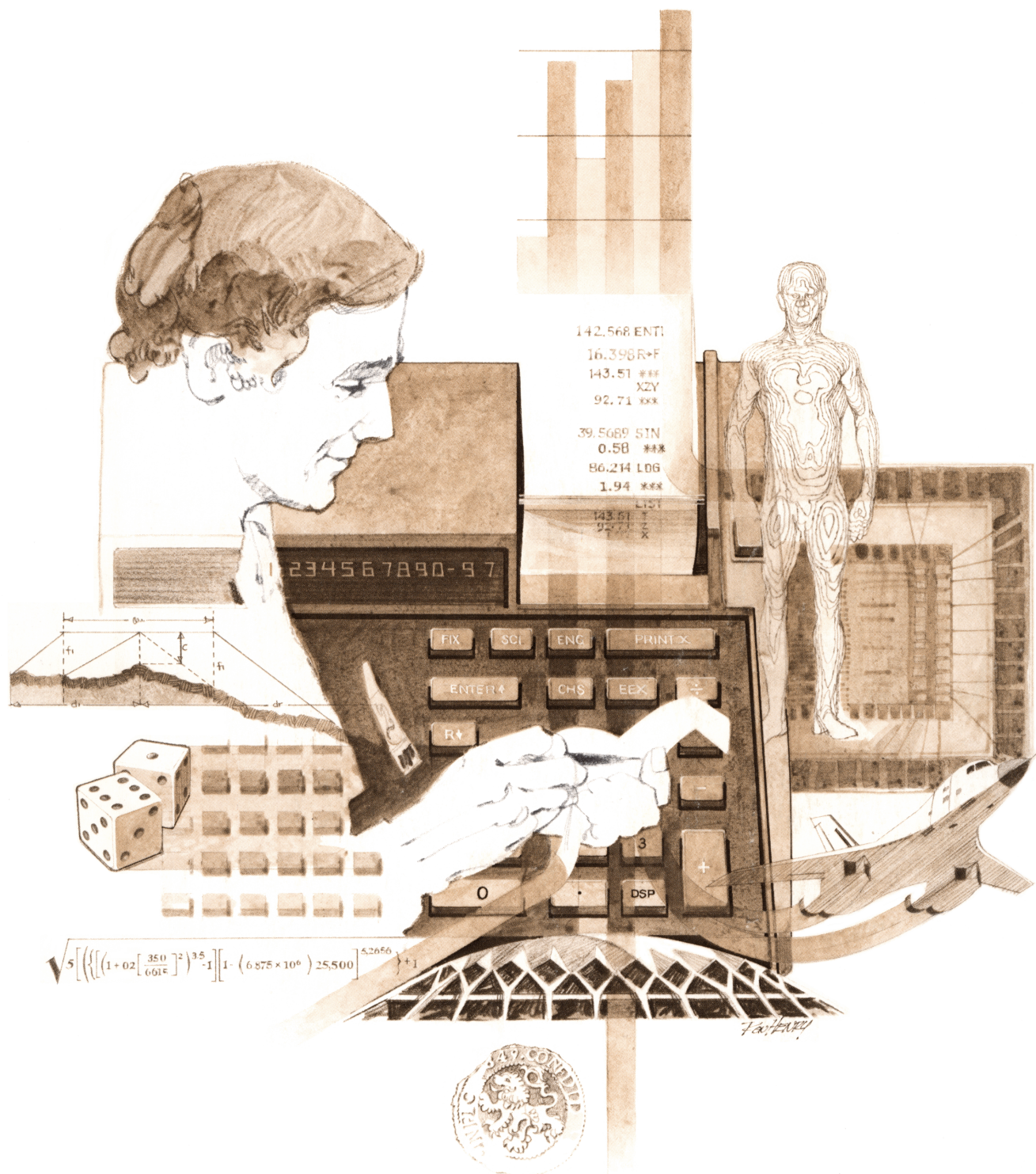


HEWLETT-PACKARD

HP-67/HP-97

Users' Library Solutions

Avigation



INTRODUCTION

In an effort to provide continued value to its customers, Hewlett-Packard is introducing a unique service for the HP fully programmable calculator user. This service is designed to save you time and programming effort. As users are aware, Programmable Calculators are capable of delivering tremendous problem solving potential in terms of power and flexibility, but the real genie in the bottle is program solutions. HP's introduction of the first handheld programmable calculator in 1974 immediately led to a request for program **solutions** — hence the beginning of the HP-65 Users' Library. In order to save HP calculator customers time, users wrote their own programs and sent them to the Library for the benefit of other program users. In a short period of time over 5,000 programs were accepted and made available. This overwhelming response indicated the value of the program library and a Users' Library was then established for the HP-67/97 users.

To extend the value of the Users' Library, Hewlett-Packard is introducing a unique service—a service designed to save you time and money. The Users' Library has collected the best programs in the most popular categories from the HP-67/97 and HP-65 Libraries. These programs have been packaged into a series of low-cost books, resulting in substantial savings for our valued HP-67/97 users.

We feel this new software service will extend the capabilities of our programmable calculators and provide a great benefit to our HP-67/97 users.

A WORD ABOUT PROGRAM USAGE

Each program contained herein is reproduced on the standard forms used by the Users' Library. Magnetic cards are not included. The Program Description I page gives a basic description of the program. The Program Description II page provides a sample problem and the keystrokes used to solve it. The User Instructions page contains a description of the keystrokes used to solve problems in general and the options which are available to the user. The Program Listing I and Program Listing II pages list the program steps necessary to operate the calculator. The comments, listed next to the steps, describe the reason for a step or group of steps. Other pertinent information about data register contents, uses of labels and flags and the initial calculator status mode is also found on these pages. Following the directions in your HP-67 or HP-97 **Owners' Handbook and Programming Guide**, "Loading a Program" (page 134, HP-67; page 119, HP-97), key in the program from the Program Listing I and Program Listing II pages. A number at the top of the Program Listing indicates on which calculator the program was written (HP-67 or HP-97). If the calculator indicated differs from the calculator you will be using, consult Appendix E of your **Owner's Handbook** for the corresponding keycodes and keystrokes converting HP-67 to HP-97 keycodes and vice versa. No program conversion is necessary. The HP-67 and HP-97 are totally compatible, but some differences do occur in the keycodes used to represent some of the functions.

A program loaded into the HP-67 or HP-97 is not permanent—once the calculator is turned off, the program will not be retained. You can, however, permanently save any program by recording it on a blank magnetic card, several of which were provided in the Standard Pac that was shipped with your calculator. Consult your **Owner's Handbook** for full instructions. A few points to remember:

The Set Status section indicates the status of flags, angular mode, and display setting. After keying in your program, review the status section and set the conditions as indicated before using or permanently recording the program.

REMEMBER! To save the program permanently, **clip** the corners of the magnetic card once you have recorded the program. This simple step will protect the magnetic card and keep the program from being inadvertently erased.

As a part of HP's continuing effort to provide value to our customers, we hope you will enjoy our newest concept.

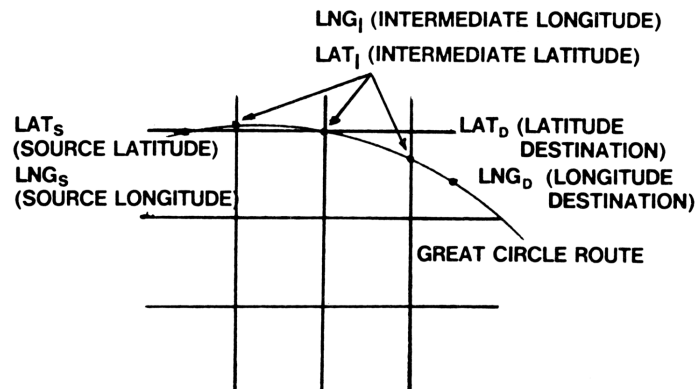
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Program Description I

Program Title Great Circle Plotting
Contributor's Name Hewlett-Packard Company, HP-67/97 Users' Library
Address 1000 N. E. Circle Boulevard
City Corvallis **State** OR **Zip Code** 97330

Program Description, Equations, Variables Given the latitude and longitude of two points on the globe and an intermediate longitude, this program calculates the latitude corresponding to the intersection of the great circle route and the intermediate longitude.



$$LAT_I = \tan^{-1} \left[\frac{(A - B)}{\sin(LNG_D - LNG_S)} \right]$$

$$A = (\tan(LAT_D) \cos(LNG_S) - \tan(LAT_S) \cos(LNG_D)) \sin(LNG_I)$$

$$B = (\tan(LAT_D) \sin(LNG_S) - \tan(LAT_S) \sin(LNG_D)) \cos(LNG_I)$$

Operating Limits and Warnings No leg may pass exactly half way around the earth, and lines of longitude may not be plotted.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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[illegible]

Sample Problem(s) On a flight from St. Helena to Bermuda, what is the latitude at 35° 17' west longitude?

	LAT	LNG
St. Helena	15° 55' S	5° 44' W
Bermuda	32° 19' N	64° 51' W

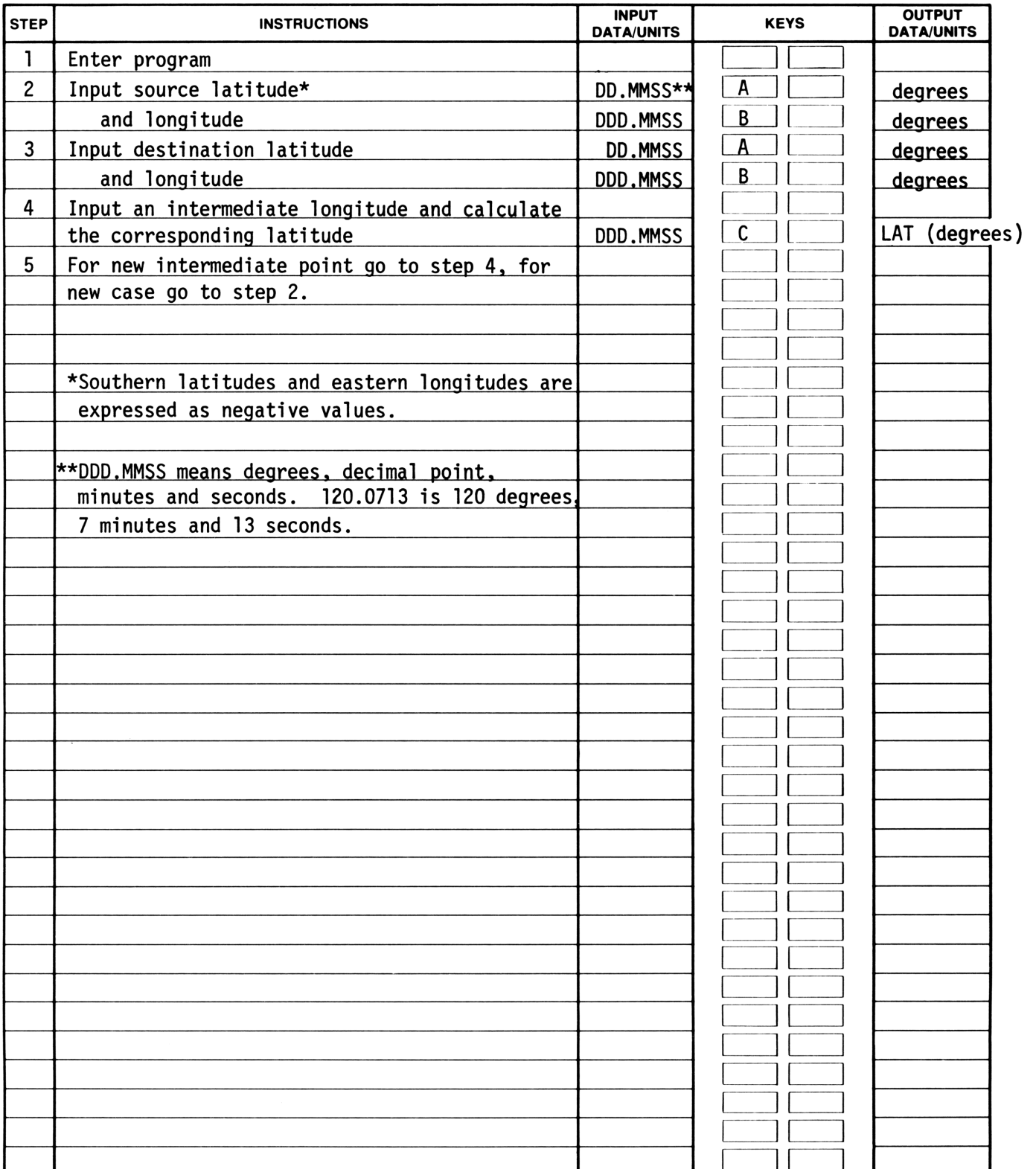
Solution(s) LAT_I = 11° 17' N

Keystrokes:	See Displayed:
15.55 [CHS] [A] 5.44 [B] 32.19 [A]	
64.51 [B] 35.17 [C]	11.17

Reference(s) _____

_____ This program is a direct translation of a program from the HP-65 _____
_____ Aviation Pac. _____

3



97 Program Listing I

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	001 *LBLA	21 11					
	002 HMS→	16 36					
	003 RCL1	36 01					
	004 ST02	35 02		060			
	005 X↔Y	-41					
	006 ST01	35 01					
	007 RTN	24					
	008 *LBLB	21 12					
	009 HMS→	16 36					
	010 RCL3	36 03					
	011 ST04	35 04					
	012 X↔Y	-41					
	013 ST03	35 03					
	014 RTN	24		070			
	015 *LBLC	21 13					
	016 HMS→	16 36					
	017 ST07	35 07					
	018 RCL4	36 04					
	019 RCL1	36 01					
	020 GSBE	23 15					
	021 RCL7	36 07					
	022 RCL3	36 03					
	023 RCL2	36 02					
	024 GSBE	23 15		080			
	025 -	-45					
	026 RCL4	36 04					
	027 RCL7	36 07					
	028 RCL1	36 01					
	029 GSBE	23 15					
	030 -	-45					
	031 RCL3	36 03					
	032 RCL7	36 07					
	033 RCL2	36 02					
	034 GSBE	23 15		090			
	035 +	-55					
	036 RCL3	36 03					
	037 RCL4	36 04					
	038 -	-45					
	039 SIN	41					
	040 ÷	-24					
	041 TAN→	16 43					
	042 ST08	35 08					
	043 →HMS	16 35					
	044 RTN	24					
	045 *LBLE	21 15					
	046 TAN	43					
	047 X↔Y	-41					
	048 COS	42					
	049 x	-35					
	050 X↔Y	-41					
	051 SIN	41					
	052 x	-35					
	053 RTN	24					

FLAGS		SET STATUS		
		FLAGS	TRIG	DISP
0		ON OFF		
1		0 <input type="checkbox"/> <input checked="" type="checkbox"/>	DEG <input checked="" type="checkbox"/>	FIX <input checked="" type="checkbox"/>
2		1 <input type="checkbox"/> <input checked="" type="checkbox"/>	GRAD <input type="checkbox"/>	SCI <input type="checkbox"/>
3		2 <input type="checkbox"/> <input checked="" type="checkbox"/>	RAD <input type="checkbox"/>	ENG <input type="checkbox"/>
		3 <input type="checkbox"/> <input checked="" type="checkbox"/>		n <u>2</u>

LABELS				
A	B	C	D	E
LAT	LNG	→LAT LNG		
a	b	c	d	e
0	1	2	3	4
5	6	7	8	9

REGISTERS									
0	1	2	3	4	5	6	7	8	9
LAT _D	LAT _S	LNG _D	LNG _S						
S0	S1	S2	S3	S4	S5	S6	S7	S8	S9
A	B	C	D	E	I				

Program Description I

Program Title	Rhumb Line Navigation		
Contributor's Name	Hewlett-Packard Company, HP-67/97 Users' Library		
Address	1000 N. E. Circle Boulevard		
City	Corvallis	State	OR Zip Code 97330

Program Description, Equations, Variables This program accepts the coordinates of two points on the globe and calculates the rhumb line heading (HDG) and distance (DIST) between them. The program inputs are latitude and longitude of the source (LAT_S , LNG_S) and latitude and longitude of the destination (LAT_D , LNG_D) in degrees, minutes, and seconds. The program outputs are heading in degrees and distance in nautical miles.

Since the rhumb line is the constant heading path between points on the globe, it forms the basis of short distance navigation. In low and mid latitudes the rhumb line is sufficient for virtually all course and distance calculations which private pilots encounter. However, as distance increases or at high latitudes, the rhumb line ceases to be an efficient flight path since it is not the shortest distance between points.

The shortest distance between points is the great circle. However, in order to fly great circles, an infinite number of heading changes are necessary. Since it is impractical to calculate an infinite number of headings at an infinite number of points, several rhumb lines may be used to approximate a great circle. The more rhumb lines that are used the closer to the great circle distance the sum of the rhumb-line distances will be. Great Circle Plotting, may be used to calculate intermediate heading change points which can be linked by rhumb lines.

Operating Limits and Warnings

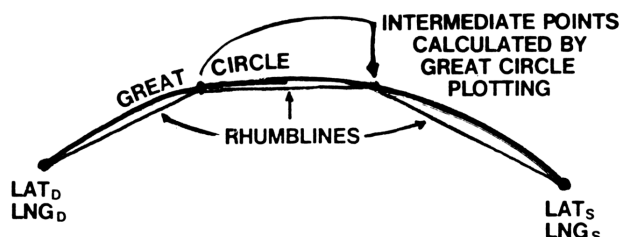
This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Program Description I

Program Title	Rhumb Line Navigation		
Contributor's Name	Hewlett-Packard Company, HP-67/97 Users' Library		
Address	1000 N. E. Circle Boulevard		
City	Corvallis	State	OR
		Zip Code	97330

Program Description, Equations, Variables



$$HDG = \tan^{-1} \left[\frac{\pi (LNG_S - LNG_D)}{180 (\ln \tan(45 + 1/2 LAT_D) - \ln \tan(45 + 1/2 LAT_S))} \right]$$

$$DIST = 60 (LAT_D - LAT_S) / \cos (HDG)$$

or, if $\cos (HDG) = 0$

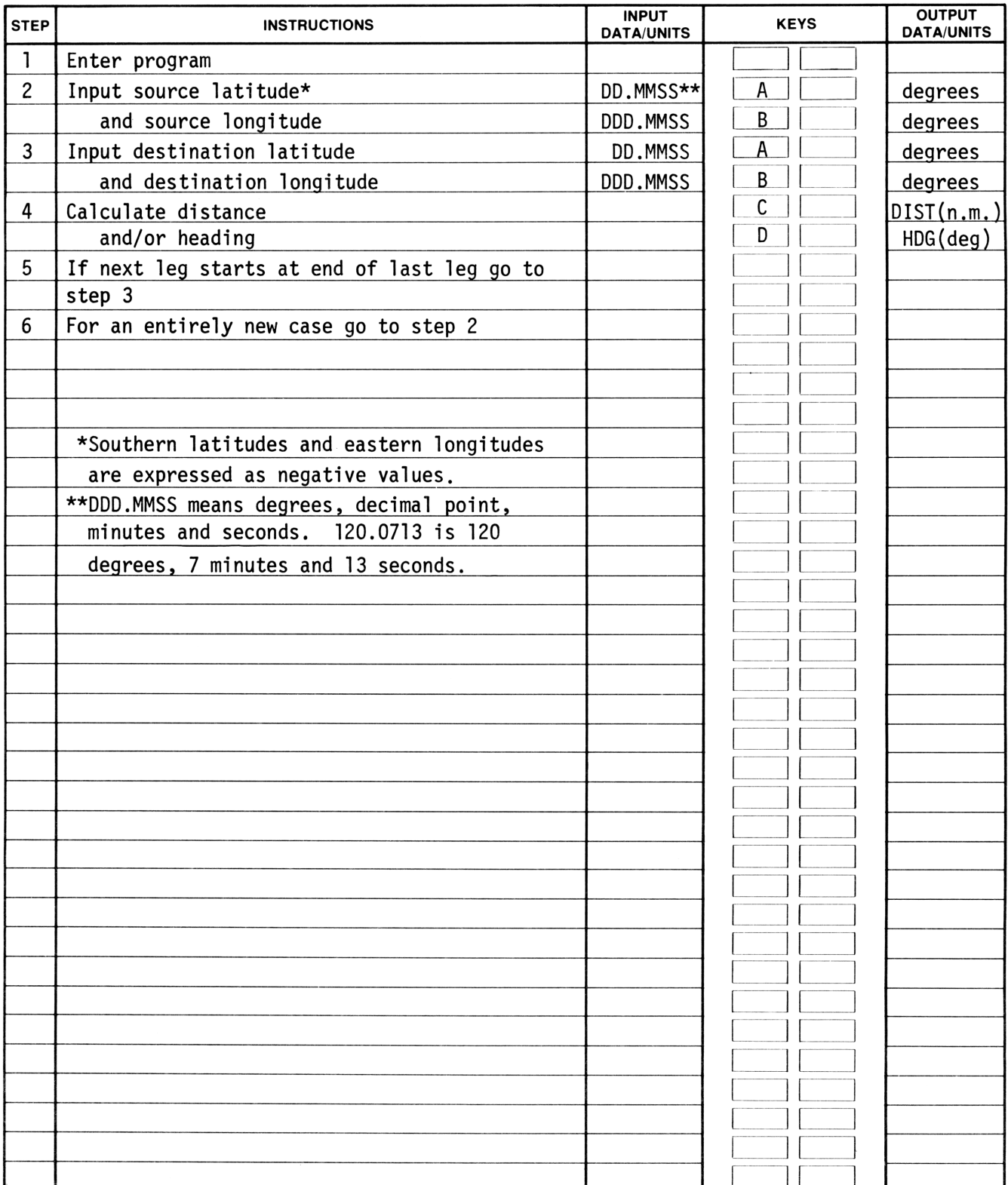
$$DIST = 60 (LNG_D - LNG_S) \cos (LAT)$$

Operating Limits and Warnings No course should pass through either the south or north pole. Errors in distance calculations may be encountered as the $\cos (HDG)$ approaches zero.

Accuracy deteriorates for legs shorter than two or three miles.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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97 Program Listing I

9

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	*LBLA	21 11		057	RTN	24	
002	HMS→	16 36		058	*LBLC	21 13	
003	RCL1	36 01		059	GSBD	23 14	
004	ST02	35 02		060	RCL7	36 07	
005	X↔Y	-41		061	RCL1	36 01	
006	ST01	35 01		062	COS	42	
007	2	02		063	x	-35	
008	÷	-24		064	RCL1	36 01	
009	4	04		065	RCL2	36 02	
010	5	05		066	-	-45	
011	+	-55		067	RCL8	36 08	
012	TAN	43		068	COS	42	
013	LN	32		069	0	00	
014	RCL5	36 05		070	X↔Y?	16-32	
015	ST06	35 06		071	GSBc	23 16 13	
016	X↔Y	-41		072	X=Y?	16-33	
017	ST05	35 05		073	R↑	16-31	
018	RCL1	36 01		074	6	06	
019	RTN	24		075	0	00	
020	*LBLB	21 12		076	x	-35	
021	HMS→	16 36		077	ABS	16 31	
022	RCL3	36 03		078	RTN	24	
023	ST04	35 04		079	*LBLc	21 16 13	
024	X↔Y	-41		080	R↓	-31	
025	ST03	35 03		081	÷	-24	
026	RTN	24		082	RTN	24	
027	*LBLD	21 14		083	*LBLd	21 16 14	
028	RCL4	36 04		084	3	03	
029	RCL3	36 03		085	6	06	
030	-	-45		086	0	00	
031	ST07	35 07		087	RTN	24	
032	2	02					
033	÷	-24		090			
034	SIN	41					
035	SIN ⁻¹	16 41					
036	9	09					
037	0	00					
038	÷	-24					
039	Pi	16-24					
040	x	-35					
041	RCL5	36 05					
042	RCL6	36 06					
043	-	-45					
044	→P	34		100			
045	R↓	-31					
046	ST08	35 08					
047	RCL7	36 07					
048	SIN	41					
049	SIN ⁻¹	16 41					
050	0	00					
051	X>Y?	16-34					
052	GSBd	23 16 14					
053	RCL8	36 08					
054	ABS	16 31					
055	-	-45					
056	ABS	16 31					

REGISTERS			
0	1 LAT _D	2 LAT _S	3 LNG _D
4 LNG _S	5 USED	6 USED	7 LNG _S -LNG _D
8 HDG	9		
S0	S1	S2	S3
S4	S5	S6	S7
S8	S9		

A	B	C	D	E	I
---	---	---	---	---	---

FLAGS		SET STATUS	
0	1	TRIG	DISP
ON OFF	ON OFF	DEG <input checked="" type="checkbox"/>	FIX <input checked="" type="checkbox"/>
0 <input type="checkbox"/> <input checked="" type="checkbox"/>	0 <input type="checkbox"/> <input checked="" type="checkbox"/>	GRAD <input type="checkbox"/>	SCI <input type="checkbox"/>
1 <input type="checkbox"/> <input checked="" type="checkbox"/>	1 <input type="checkbox"/> <input checked="" type="checkbox"/>	RAD <input type="checkbox"/>	ENG <input type="checkbox"/>
2 <input type="checkbox"/> <input checked="" type="checkbox"/>	2 <input type="checkbox"/> <input checked="" type="checkbox"/>		n <u>2</u>
3 <input type="checkbox"/> <input checked="" type="checkbox"/>	3 <input type="checkbox"/> <input checked="" type="checkbox"/>		

Program Description I

Program Title Great Circle Navigation

Contributor's Name Hewlett-Packard

Address 1000 N.E. Circle Blvd.

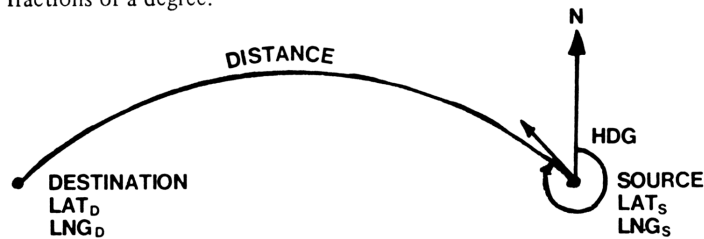
City Corvallis

State Oregon

Zip Code 97330

Program Description, Eq

This program computes the great circle distance between two points and computes the initial heading from the first point. Coordinates are input in degrees, minutes and seconds north or south of the equator and east or west of the prime meridian. Outputs are distances in nautical miles and headings in degrees and decimal fractions of a degree.



The great circle distance in nautical miles between two points is given by

$$\text{DIST} = 60 \cos^{-1} [\sin \text{LAT}_S \sin \text{LAT}_D + \cos \text{LAT}_S \cos \text{LAT}_D \cos(\text{LNG}_D - \text{LNG}_S)]$$

Where

LAT_S and LAT_D are the source and destination latitudes and LNG_S and LNG_D are the source and destination longitudes.

Correspondingly, the initial heading from the source to destination is

$$\text{HDG} = \cos^{-1} \left[\frac{\sin \text{LAT}_D - \sin \text{LAT}_S \cos (\text{DIST}/60)}{\sin (\text{DIST}/60) \cos \text{LAT}_S} \right]$$

NOTE: If $\sin (\text{LNG}_S - \text{LNG}_D) < 0$ then $\text{HDG} = 360 - \text{HDG}$

Operating Limits and V

Limits and Warnings

Truncation and round off errors occur when the source and destination are very close together (1 mile or less). Input data is in degrees, minutes and seconds, not degrees, minutes and tenths of minutes. North latitudes and west longitudes are positive numbers, south latitudes and east longitudes are negative numbers.

Do not use coordinates located at diametrically opposite sides of the earth. Do not use latitudes at $+90^\circ$ or -90° (i.e., North and South Poles).

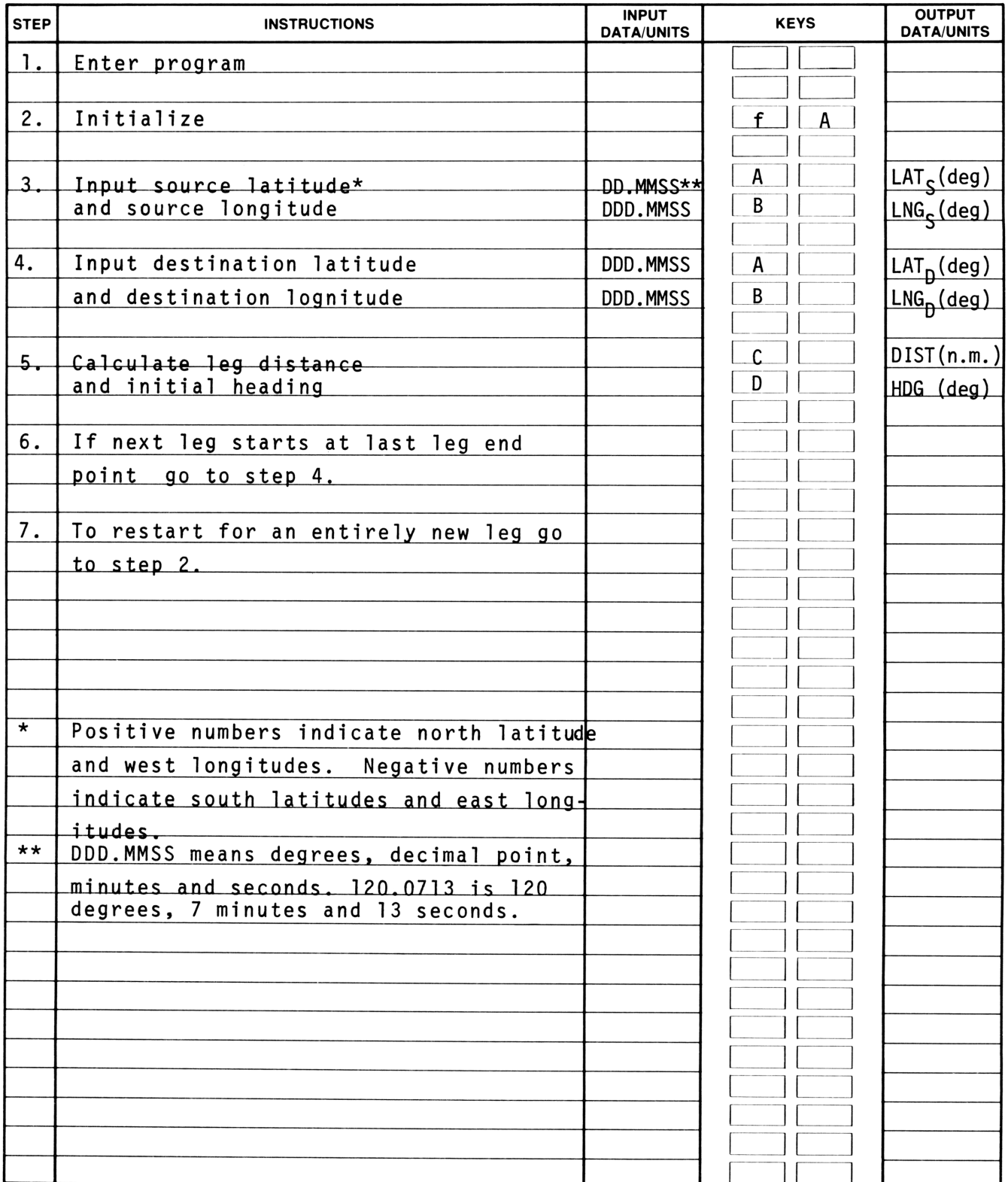
This program may give flashing zeros when trying to compute headings along lines of longitude.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Reference(s)

This program is a direct translation of a program from the HP-65
Aviation Pac.



97 Program Listing I

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STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	*LBLA	21 16 11		057	3	03	
002	CF2	16 22 02		058	6	06	
003	CLRG	16-53		059	0	00	
004	DEG	16-21		060	GSBC	23 13	
005	CLX	-51		061	R↓	-31	
006	RTN	24		062	ENT↑	-21	
007	*LBLA	21 11		063	COS	42	
008	HMS→	16 36		064	RCL8	36 08	
009	RCL1	36 01		065	x	-35	
010	ST02	35 02		066	RCL7	36 07	
011	X→Y	-41		067	X→Y	-41	
012	ST01	35 01		068	-	-45	
013	RTN	24		069	X→Y	-41	
014	*LBLB	21 12		070	SIN	41	
015	HMS→	16 36		071	÷	-24	
016	RCL3	36 03		072	RCL6	36 06	
017	ST04	35 04		073	÷	-24	
018	X→Y	-41		074	COS←	16 42	
019	ST03	35 03		075	F2?	16 23 02	
020	RTN	24		076	-	-45	
021	*LBLC	21 13		077	RTN	24	
022	RCL4	36 04					
023	RCL3	36 03					
024	-	-45					
025	ENT↑	-21					
026	SIN	41					
027	0	00					
028	X→Y?	16-34					
029	SF2	16 21 02					
030	+	-55					
031	CLX	-51					
032	+	-55					
033	COS	42					
034	RCL2	36 02					
035	COS	42					
036	ST06	35 06					
037	x	-35					
038	RCL1	36 01					
039	COS	42					
040	x	-35					
041	RCL1	36 01					
042	SIN	41					
043	ST07	35 07					
044	RCL2	36 02					
045	SIN	41					
046	ST08	35 08					
047	x	-35					
048	+	-55					
049	COS←	16 42					
050	ENT↑	-21					
051	ENT↑	-21					
052	6	06					
053	0	00					
054	x	-35					
055	RTN	24					
056	*LBLD	21 14					

REGISTERS			
0	1 LAT _D	2 LAT _S	3 LNG _D
S0	S1	S2	S3
A	B	C	D

SET STATUS			
0	1	2	3
ON OFF	ON OFF	ON OFF	ON OFF
0 <input type="checkbox"/> <input checked="" type="checkbox"/>	0 <input type="checkbox"/> <input checked="" type="checkbox"/>	0 <input type="checkbox"/> <input checked="" type="checkbox"/>	0 <input type="checkbox"/> <input checked="" type="checkbox"/>
1 <input type="checkbox"/> <input checked="" type="checkbox"/>	1 <input type="checkbox"/> <input checked="" type="checkbox"/>	1 <input type="checkbox"/> <input checked="" type="checkbox"/>	1 <input type="checkbox"/> <input checked="" type="checkbox"/>
2 <input type="checkbox"/> <input checked="" type="checkbox"/>	2 <input type="checkbox"/> <input checked="" type="checkbox"/>	2 <input type="checkbox"/> <input checked="" type="checkbox"/>	2 <input type="checkbox"/> <input checked="" type="checkbox"/>
3 <input type="checkbox"/> <input checked="" type="checkbox"/>	3 <input type="checkbox"/> <input checked="" type="checkbox"/>	3 <input type="checkbox"/> <input checked="" type="checkbox"/>	3 <input type="checkbox"/> <input checked="" type="checkbox"/>

SET STATUS			
TRIG	DISP		
DEG <input checked="" type="checkbox"/>	FIX <input checked="" type="checkbox"/>		
GRAD <input type="checkbox"/>	SCI <input type="checkbox"/>		
RAD <input type="checkbox"/>	ENG <input type="checkbox"/>		
	n <u>2</u>		

Program Description I

Program Title	Position Given Heading, Speed, and Time		
Contributor's Name	Hewlett-Packard		
Address	1000 N.E. Circle Blvd.		
City	Corvallis	State	Oregon
		Zip Code	97330

Program Description	<p>Given the starting position (LAT_S, LNG_S), the heading, the speed and the time of travel, the destination position (LAT_D, LNG_D) is calculated by a rhumbline.</p> $LAT_D = \left(\frac{\text{Time} \times \text{Speed} \times \cos \text{HDG}}{60} \right) + LAT_S$ $LNG_D = LNG_S - \frac{180}{\pi} \left[(\tan \text{HDG}) \times (\ln \tan(45 + \frac{1}{2} LAT_D)) - \ln \tan(45 + \frac{1}{2} LAT_S) \right]$ <p>If $\text{HDG} = 90^\circ$ or 270° then,</p> $LNG_D = \frac{\text{DIST}}{60 \cos LAT} + LNG_S$ <p>HDG = Heading</p> <p>Speed = Speed in knots</p> <p>Time = Time in hours</p> <p>DIST = Speed x Time</p>
Operating Limits and Warnings	<p>Limits and Warnings</p> <p>The path of flight may not cross a pole.</p>

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Program Description II

Sketch(es)

Sample Problem(s)

Sample Problem

Starting at 30° N, 140° W, flying at 500 knots with a heading of 237 degrees what is the position after two hours?

Solution(s)

Solution

20° 55' N, 155° 30' W

Keystrokes

30 **A** 140 **A** 237 **B** 500 **C** 2 **D**
D

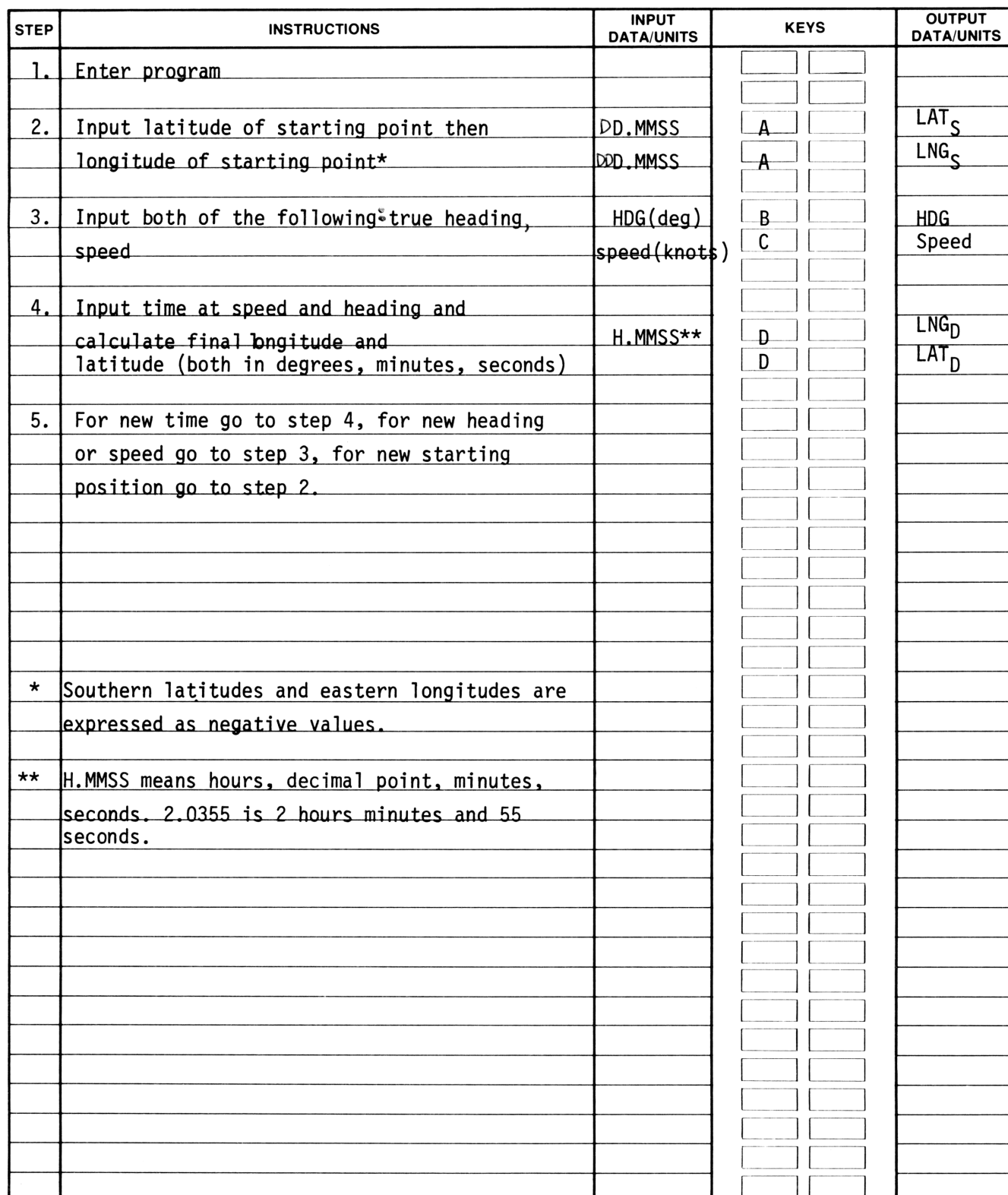
See Displayed

155.30

20.55

Reference(s)

This program is a direct translation of a program from the HP-65 Aviation Pac.



97 Program Listing I

17

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	*LBLA	21 11		057	+	-55	
002	HMS→	16 36		058	1	01	
003	RCL4	36 04		059	→R	44	
004	ST02	35 02		060	→P	34	
005	X→Y	-41		061	R↓	-31	
006	ST04	35 04		062	ST03	35 03	
007	RTN	24		063	→HMS	16 35	
008	*LBLB	21 12		064	RTN	24	
009	ST05	35 05		065	*LBLD	21 14	
010	RTN	24		066	RCL1	36 01	
011	*LBLC	21 13		067	→HMS	16 35	
012	ST06	35 06		068	RTN	24	
013	RTN	24		069	*LBLE	21 15	
014	*LBLD	21 14		070	2	02	
015	HMS→	16 36		071	÷	-24	
016	RCL6	36 06		072	4	04	
017	x	-35		073	5	05	
018	ST07	35 07		074	+	-55	
019	RCL5	36 05		075	TAN	43	
020	COS	42		076	LN	32	
021	x	-35		077	RTN	24	
022	6	06					
023	0	00		080			
024	÷	-24					
025	RCL2	36 02					
026	+	-55					
027	SIN	41					
028	SIN→	16 41					
029	ST01	35 01					
030	GSBE	23 15					
031	RCL2	36 02					
032	GSBE	23 15					
033	X=Y?	16-33					
034	GT01	22 01		090			
035	-	-45					
036	RCL5	36 05					
037	TAN	43					
038	x	-35					
039	Pi	16-24					
040	÷	-24					
041	1	01					
042	8	08					
043	0	00					
044	x	-35		100			
045	GT02	22 02					
046	*LBL1	21 01					
047	RCL7	36 07					
048	RCL2	36 02					
049	COS	42					
050	÷	-24					
051	6	06					
052	0	00					
053	÷	-24					
054	*LBL2	21 02					
055	CHS	-22					
056	RCL4	36 04					

REGISTERS			
0	1	2	3
S0	S1	S2	S3
A	B	C	D

SET STATUS			
0	1	2	3
ON	OFF	TRIG	DISP
0	<input type="checkbox"/>	DEG	FIX
1	<input checked="" type="checkbox"/>	GRAD	SCI
2	<input type="checkbox"/>	RAD	ENG
3	<input checked="" type="checkbox"/>		n

Program Description I

Program Title Line of Sight Distance

Contributor's Name Hewlett-Packard

Address 1000 N.E. Circle Blvd.

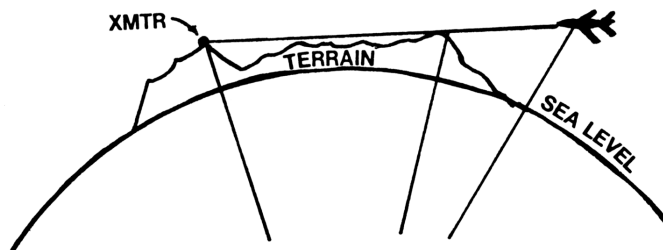
City Corvallis

State Oregon

Zip Code 97330

Program Description

This program calculates either the aircraft altitude or the line-of-sight distance from an aircraft to a transmitting station. The inputs are the transmitter height (MSL), terrain height (MSL), and either the line-of-sight distance (n.m.) or the aircraft altitude in feet above MSL.



If

$$R_p = R + ALT$$

$$R_g = R + TER$$

$$R_t = R + XTMR$$

where

R = earth's radius = 3440 n.m.

ALT = aircraft altitude

TER = terrain altitude

$XMTR$ = transmitter altitude

Operating Limits and Warnings

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Program Description I

Program Title _____

Contributor's Name _____

Address _____

City _____

State _____

Zip Code _____

Program Description, Equations, Variables _____

Since R_g is perpendicular to the line-of-sight

$$\text{DIST} = \sqrt{R_p^2 - R_g^2} + \sqrt{R_t^2 - R_g^2}$$

and

$$\text{ALT} = \sqrt{R_g^2 + (D - \sqrt{R_t^2 - R_g^2})^2}$$

Operating Limits and Warnings Terrain input must not exceed either transmitter height or aircraft altitude. Any attempts to do so will result in an "error" display. This program does not account for refraction of radio waves.

The terrain input yields a worst case answer. If the terrain is close to either the station or the aircraft, the program will calculate a shorter distance or higher altitude than is actually necessary.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Program Description II

Sketch(es)

Sample Problem(s)

An omnidirectional antenna is 2000 feet high. The surrounding terrain is 1000 feet high. How high must you be to receive the transmission from a distance of 100 n.m?

Solution(s)

ALT = 4887.18 feet

Keystrokes

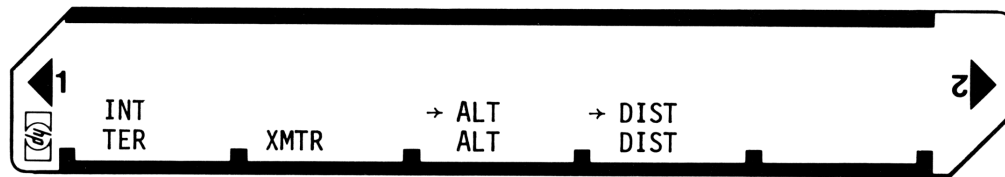
[f] [A] 1000 [A] 2000 [B] 100 [D] [f] [C]

See Display

4887.18

Reference(s)

This program is a direct translation of a program from the HP-65 Aviation Pac.

[illegible]

97 Program Listing I

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	*LBLa	21 16 11		057	RCL4	36 04	
002	CLRG	16-53		058	RCL8	36 08	
003	6	06		059	-	-45	
004	0	00		060	JX	54	
005	7	07		061	RCL3	36 03	
006	6	06		062	RCL8	36 08	
007	ST06	35 06		063	-	-45	
008	3	03		064	JX	54	
009	4	04		065	+	-55	
010	4	04		066	RCL6	36 06	
011	0	00		067	÷	-24	
012	x	-35		068	RTN	24	
013	ST07	35 07					
014	1	01		070			
015	RTN	24					
016	*LBLA	21 11					
017	ST01	35 01					
018	RCL7	36 07					
019	+	-55					
020	X²	53					
021	ST08	35 08					
022	RCL1	36 01					
023	RTN	24					
024	*LBLB	21 12		080			
025	ST02	35 02					
026	RCL7	36 07					
027	+	-55					
028	X²	53					
029	ST04	35 04					
030	RCL2	36 02					
031	RTN	24					
032	*LBLC	21 13					
033	RCL7	36 07					
034	+	-55		090			
035	X²	53					
036	ST03	35 03					
037	RTN	24					
038	*LBLc	21 16 13					
039	RCL4	36 04					
040	RCL8	36 08					
041	-	-45					
042	JX	54					
043	RCL5	36 05					
044	-	-45		100			
045	RCL8	36 08					
046	JX	54					
047	→P	34					
048	RCL7	36 07					
049	-	-45					
050	RTN	24					
051	*LBLD	21 14					
052	RCL6	36 06					
053	x	-35					
054	ST05	35 05					
055	RTN	24					
056	*LBLd	21 16 14					

REGISTERS			
0	1	2	3
S0	S1	S2	S3
A	B	C	D

0	1	2	3	4	5	6	7	8	9
S0	S1	S2	S3	S4	S5	S6	S7	S8	S9
A	B	C	D	E	F	G	H	I	J

FLAGS				SET STATUS			
0	1	2	3	ON	OFF	TRIG	DISP
				0	<input type="checkbox"/>	DEG	<input checked="" type="checkbox"/>
				1	<input type="checkbox"/>	GRAD	<input type="checkbox"/>
				2	<input type="checkbox"/>	RAD	<input type="checkbox"/>
				3	<input type="checkbox"/>		
						FIX	<input checked="" type="checkbox"/>
						SCI	<input type="checkbox"/>
						ENG	<input type="checkbox"/>
						n	2

Program Description I

Program Title Position and/or Navigation by Two VOR's

Contributor's Name Hewlett-Packard

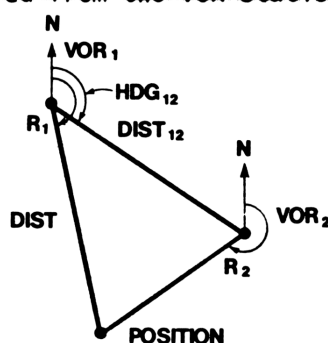
Address 1000 N.E. Circle Blvd.

City Corvallis

State Oregon

Zip Code 97330

Program Description, Equations, Variables This program finds the distance from one of two VOR's to an aircraft and may be used to navigate between any two points, provided signals can be received from two VOR stations.



$$DIST = \left| \frac{DIST_{12} \sin(R_2 - HDG_{12})}{\sin(R_2 - R_1)} \right|$$

where

R_1 = Radial from VOR₁

R_2 = Radial from VOR₂

HDG_{12} = Heading between VORs

$DIST_{12}$ = Distance between VORs

$DIST$ = Distance from VOR₁ to aircraft

Operating Limits and Warnings

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Program Description I

Program Title **Navigation by Two VORs**

Contributor's Name

Address

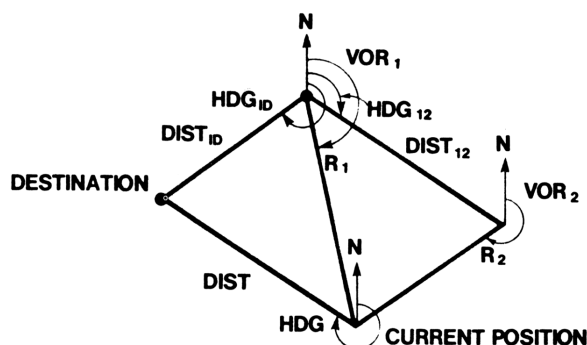
City

State

Zip Code

Program Description, Equations, Variables

This program may be used to navigate between any two points provided signals can be received from two VOR stations.



$$D_1 = \left| \frac{\text{DIST}_{12} \sin(R_2 - \text{HDG}_{12})}{\sin(R_2 - R_1)} \right|$$

$$\overrightarrow{\text{DIST}} = \vec{D}_1 + \overrightarrow{\text{DIST}_{1D}}$$

where

DIST_{12} = Distance between VORs

HDG_{12} = Heading between VORs

R_1 = Radial from VOR₁

R_2 = Radial from VOR₂

D_1 = Distance from VOR₁ to aircraft

\vec{D}_1 = Aircraft position vector with respect to VOR₁

$\overrightarrow{\text{DIST}_{1D}}$ = Destination position vector with respect to VOR₁

$\overrightarrow{\text{DIST}}$ = Required flight vector to destination

Operating Limits and Warnings

The VORs must not be in a straight line from the aircraft.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Program Description II

Sketch(es)

Sample Problem(s) / **Sample Problem**

$R_1 = 170$ degrees
 $R_2 = 240$ degrees
 $DIST_{12} = 27$ n.m.
 $HDG_{12} = 125$ degrees

What is the distance from VOR_1 ?

2. **Sample Problem**

$R_1 = 170$ degrees
 $R_2 = 250$ degrees
 $DIST_{12} = 13$ n.m.
 $HDG_{12} = 145$ degrees
 $HDG_{1D} = 255$ degrees
 $DIST_{1D} = 20$ n.m.

Find the heading and distance to the destination.

Solution(s)

1. **Solution**

$DIST = 26$ n.m.

2. **Solution**

$HDG = 289$
 $DIST = 23$ n.m.

Reference(s)

This program is a direct translation of a program from the HP-65
Aviation Pac.

Program Description II

Sketch(es)

Sample Problem(s)

Solution(s)	Keystrokes	See Displayed
1.	[f] [A] 170 [A] 240 [A] 27 [B] 125 [C] [f] [C]	26
2.	[f] [A] 170 [A] 250 [A] 13 [B] 145 [C] 255 [D]	
	20 [D] [E]	289
	[E]	23

Reference(s)

27

[illegible]

97 Program Listing I

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	*LBLa	21 16 11		057	ST07	35 07	
002	DSP0	-63 00		058	XZY	-41	
003	CLX	-51		059	ST08	35 08	
004	RTN	24		060	9	09	
005	*LBLA	21 11		061	0	00	
006	ST01	35 01		062	RCL5	36 05	
007	RTN	24		063	-	-45	
008	*LBLA	21 11		064	RCL6	36 06	
009	ST02	35 02		065	→R	44	
010	RTN	24		066	ST+7	35-55 07	
011	*LBLB	21 12		067	XZY	-41	
012	ST03	35 03		068	ST+8	35-55 08	
013	RTN	24		069	RCL8	36 08	
014	*LBLC	21 13		070	RCL7	36 07	
015	ST04	35 04		071	→P	34	
016	RTN	24		072	XZY	-41	
017	*LBLc	21 16 13		073	9	09	
018	RCL2	36 02		074	0	00	
019	RCL4	36 04		075	XZY	-41	
020	-	-45		076	-	-45	
021	SIN	41		077	0	00	
022	RCL3	36 03		078	XZY	-41	
023	x	-35		079	XZY?	16-35	
024	RCL2	36 02		080	GSBe	23 16 15	
025	RCL1	36 01		081	ST07	35 07	
026	-	-45		082	R↓	-31	
027	SIN	41		083	R↓	-31	
028	÷	-24		084	ST08	35 08	
029	ABS	16 31		085	RCL7	36 07	
030	RTN	24		086	RTN	24	
031	*LBLD	21 14		087	*LBLE	21 15	
032	ST05	35 05		088	RCL8	36 08	
033	RTN	24		089	RTN	24	
034	*LBLD	21 14		090	*LBLe	21 16 15	
035	ST06	35 06		091	3	03	
036	RTN	24		092	6	06	
037	*LBLE	21 15		093	0	00	
038	RCL3	36 03		094	+	-55	
039	RCL1	36 01		095	RTN	24	
040	RCL2	36 02					
041	-	-45					
042	SIN	41					
043	÷	-24					
044	RCL2	36 02					
045	RCL4	36 04					
046	-	-45					
047	SIN	41					
048	x	-35					
049	ABS	16 31					
050	2	02					
051	7	07					
052	0	00					
053	RCL1	36 01					
054	-	-45					
055	XZY	-41					
056	→R	44					

REGISTERS									
0	1	2	3	4	5	6	7	8	9
	R ₁	R ₂	DEST ₁₂	HDG ₁₂	HDG ₁₀	DEST ₁₀	USRP	USRD	
S0	S1	S2	S3	S4	S5	S6	S7	S8	S9
A	B	C	D	E	I				

Program Description I

29

Program Title Position by One Vor

Contributor's Name Hewlett-Packard

Address 1000 N.E. Circle Blvd.

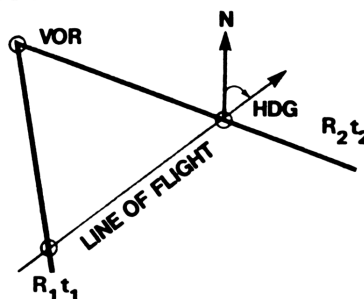
City Corvallis

State Oregon

Zip Code 97330

Program Description, Equations, Variables

This program computes the distance from a VOR station to an aircraft. The distance is found in a manner similar to the classical situation where one flies at right angles to the VOR radial and computes the time to the VOR from the time between bearings and the degrees of bearing change. This program offers a more complete solution in that it is unnecessary to fly at right angles to the VOR station and it includes the effect of winds.



The distance from the VOR station to the airplane is given by

$$S = \frac{(GS \times \Delta t) \sin(C - R_1)}{\sin(R_1 - R_2)} \quad (1)$$

where

GS = ground speed of aircraft

Δt = time between readings = $t_2 - t_1$

C = magnetic course of aircraft

R_1 = first radial to the VOR

R_2 = second radial to the VOR

t_1 = time of the first VOR radial intercept.

t_2 = time of the second VOR radial intercept.

Operating Limits and Warnings

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Program Description I

Program Title Position by One VOR

Contributor's Name Hewlett-Packard

Address 1000 N.E. Circle Blvd.

City Corvallis

State Oregon

Zip Code 97330

Program Description, Equations, Variables

Ground speed and course are found from the polar representation:

$$\frac{GS}{60} \angle C = TAS \angle HDG - W \angle D - V \quad (2)$$

where

- V = magnetic variation
- TAS = true airspeed
- HDG = aircraft heading
- W = wind velocity
- D = wind direction (true)
- \angle should be read as "at angle".

Although the ground speed vector is the true airspeed vector *plus* the wind vector, equation (2) is correct because the wind direction D indicates the direction the wind is coming from, not the direction it is blowing toward.

Operating Limits and Warnings

Limits and Warnings

Overall accuracy is limited by VOR receiver resolution. The difference in VOR readings should be at least 5° and preferably 10° to obtain accurate results. Times must be input to the nearest second.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Program Description II

Sketch(es)

Sample Problem(s)

An airplane is flying at a heading of 35° . Its true airspeed is 150 knots. The reported winds are 240° at 19 knots. Magnetic variation is 15° west. At 3:22:10 the OMNI indicates a heading of 330° to the station. At 3:34:30 the VOR reads 240° to the station. What is the distance to the station at the time of the second reading?

Solution(s)

31.72 nautical miles

Keystrokes

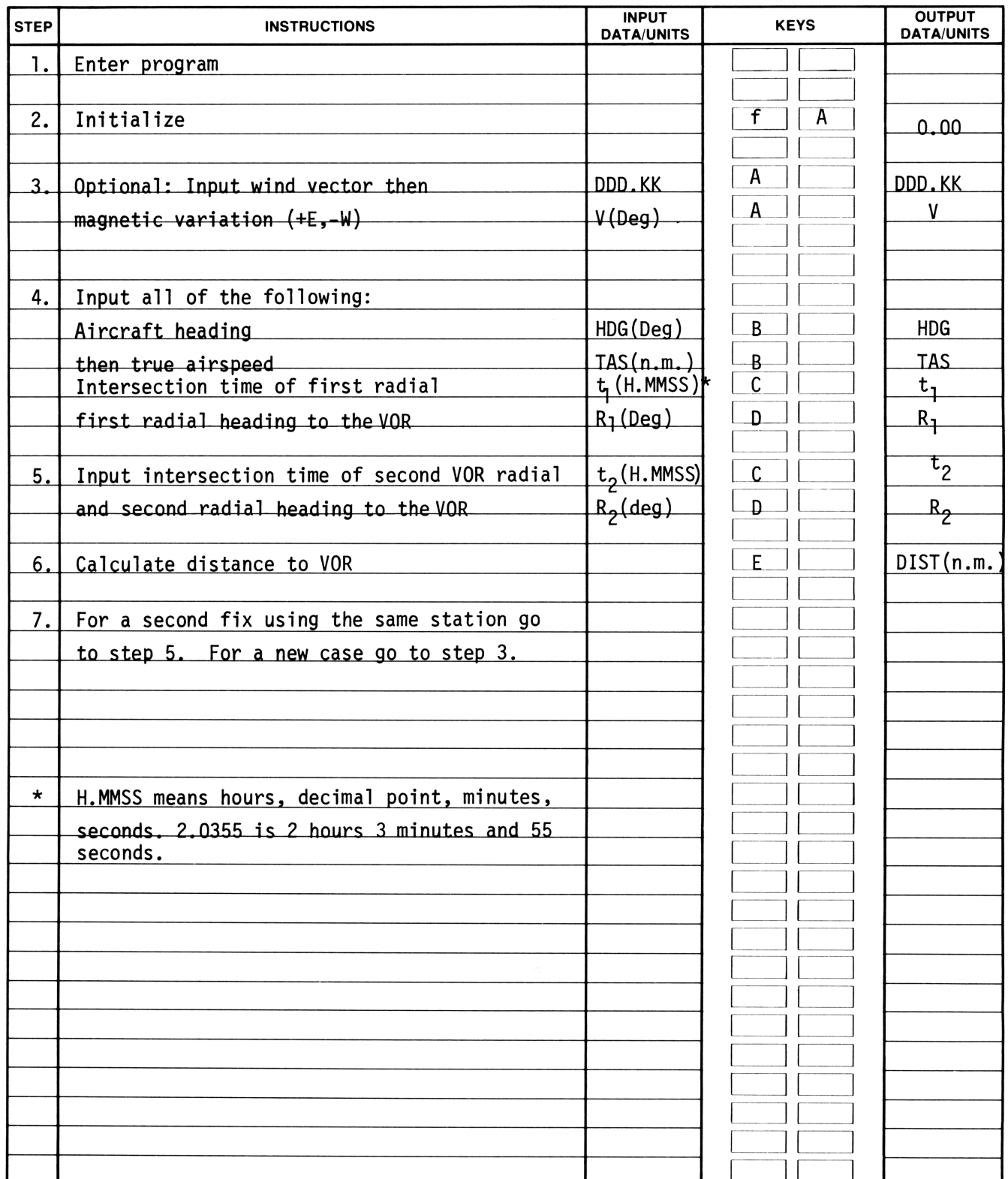
[f] [A] 240.19 [A] 15 [CHS] [A] 35 [B] 150 [B]
3.2210 [C] 330 [D] 3.3430 [C] 240 [D] [E]

See Display

31.72

Reference(s)

This program is a direct translation of a program from the HP-65 Aviation Pac.



97 Program Listing I

33

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	*LBLA	21 16 11		057	HMS+	16-55	
002	CLX	-51		058	HMS+	16 36	
003	ST01	35 01		059	ENT↑	-21	
004	ST02	35 02		060	CLX	-51	
005	DEG	16-21		061	X>Y?	16-34	
006	RTN	24		062	GSBe	23 16 15	
007	*LBLA	21 11		063	+	-55	
008	ST02	35 02		064	x	-35	
009	RTN	24		065	X≠Y	-41	
010	*LBLA	21 11		066	RCL7	36 07	
011	ST01	35 01		067	-	-45	
012	RTN	24		068	SIN	41	
013	*LBLB	21 12		069	x	-35	
014	ST04	35 04		070	RCL7	36 07	
015	RTN	24		071	RCL8	36 08	
016	*LBLB	21 12		072	-	-45	
017	ST03	35 03		073	SIN	41	
018	RTN	24		074	÷	-24	
019	*LBLC	21 13		075	RTN	24	
020	RCL6	36 06		076	*LBLc	21 16 15	
021	ST05	35 05		077	CLX	-51	
022	X≠Y	-41		078	2	02	
023	ST06	35 06		079	4	04	
024	RTN	24		080	RTN	24	
025	*LBLD	21 14					
026	RCL8	36 08					
027	ST07	35 07					
028	X≠Y	-41					
029	ST08	35 08					
030	RTN	24					
031	*LBLE	21 15					
032	RCL2	36 02					
033	INT	16 34					
034	RCL1	36 01		090			
035	-	-45					
036	RCL2	36 02					
037	FRC	16 44					
038	EEX	-23					
039	2	02					
040	x	-35					
041	CHS	-22					
042	÷R	44					
043	RCL4	36 04					
044	RCL3	36 03		100			
045	÷R	44					
046	X≠Y	-41					
047	R↑	16-31					
048	+	-55					
049	R↓	-31					
050	+	-55					
051	R↑	16-31					
052	X≠Y	-41					
053	÷P	34					
054	RCL6	36 06					
055	RCL5	36 05					
056	CHS	-22					

REGISTERS			
0	1	2	3
	V _{DEG}	DDO.KK	TAS
4	5	6	7
H _{DG}	T ₁	T ₂	R ₁
8	9		
R ₂			

S0	S1	S2	S3	S4	S5	S6	S7	S8	S9

A	B	C	D	E	I

FLAGS		SET STATUS		
0		FLAGS		DISP
		ON OFF		
0	<input type="checkbox"/>	DEG	<input checked="" type="checkbox"/>	FIX <input checked="" type="checkbox"/>
1	<input type="checkbox"/>	GRAD	<input type="checkbox"/>	SCI <input type="checkbox"/>
2	<input type="checkbox"/>	RAD	<input type="checkbox"/>	ENG <input type="checkbox"/>
3	<input type="checkbox"/>			n <u>2</u>

Program Description I

Program Title	D M E Speed Correction		
Contributor's Name	Hewlett-Packard		
Address	1000 N.E. Circle Blvd.		
City	Corvallis	State	Oregon
		Zip Code	97330

Program Description, Equ	<p>The program calculates ground speed from the DME speed indicator when the airplane course is not directly to or from a DME station.</p> <p>The DME speed indicator reads the component of velocity that is on a line between the plane and the DME station. The component V_1 is given by:</p> $V_1 = GS \times \cos(D - C) $ <p>where</p> <p>GS = The aircraft speed D = Direction to (or from) the DME station C = Aircraft ground course</p> <p>solving for GS</p> $GS = \frac{V_1}{ \cos(D - C) }$ <p>The program will also correct for aircraft altitude</p> $GS' = \frac{GS \sqrt{\Delta h^2 + DIST^2}}{DIST}$ <p>where</p> <p>GS' = Aircraft ground speed corrected for heading and elevation Δh = Difference between aircraft and DME altitude. DIST = Distance to DME</p>
Operating Limits and Warnings	<p>Limits and Warnings</p> <p>The accuracy of the DME and the limits of measuring D and C cause errors when angles to DME radials approach 90 degrees. To obtain accurate values, you should only use data obtained when crossing DME radials at an angle less than 60°.</p> <p>The program uses ground course as an input, not aircraft heading. Aircraft headings must be corrected by the wind correction angle to obtain ground course.</p>

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Program Description II

Sketch(es)

Sample Problem(s)

An airplane flying a course of 265° intercepts the 220° TO radial of a DME station. .
The indicated DME speed is 123 knots. What is the ground speed.

If you are 10,000 feet above the DME station and 7 n.m. away what is your ground speed?

Solution(s)

GS = 174 knots

GS' = 179 knots

Keystrokes

[f] [A] 265 [A] 220 [B] 123 [C]
7 [D] 10000 [E]

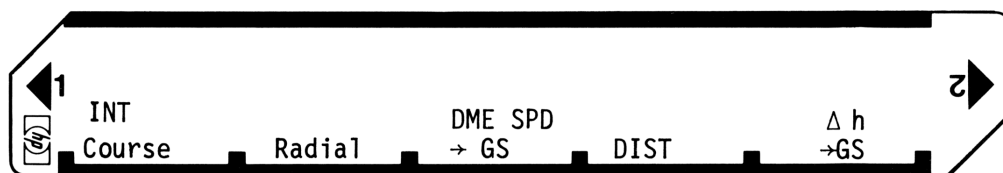
See Display

174

179

Reference(s)

This program is a direct translation of a program from the HP-65 Aviation Pac.

[illegible]

37

[illegible]

Program Description I

Program Title Average Wind Vector

Contributor's Name Hewlett-Packard

Address 1000 N.E. Circle Blvd.

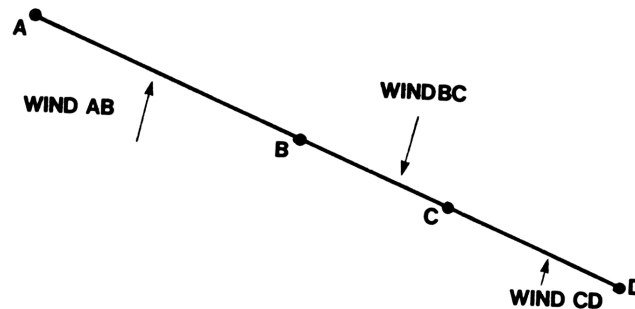
City Corvallis

State Oregon

Zip Code 97330

Program Description, Equations, Variables

When planning a flight it may be helpful to reduce several reported wind vectors along the flight path to one average wind. By weighting each wind vector along the flight path according to the distance it acts, an approximate average wind vector can be found. For a flight from A to D with forecast winds as shown:



$$\overrightarrow{\text{Wind Ave}} = \frac{1}{\text{Dist}_{AD}} \left[(\text{Dist}_{AB})(\overrightarrow{\text{Wind}_{AB}}) + (\text{Dist}_{BC})(\overrightarrow{\text{Wind}_{BC}}) + (\text{Dist}_{CD})(\overrightarrow{\text{Wind}_{CD}}) \right]$$

Operating Limits and Warnings

Limits and Warnings

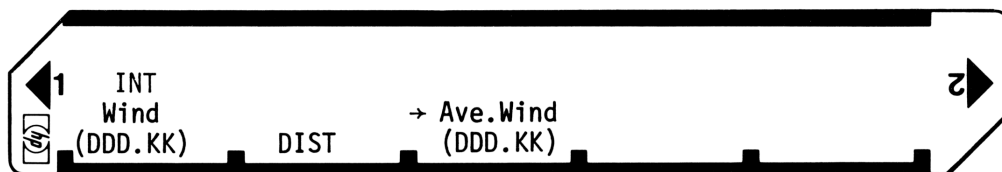
The greater the aircraft velocity as compared to that of the wind, the closer the approximation is to the actual case.

The velocity of input winds must be less than 100.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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User Instructions

[illegible]

97 Program Listing I

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STEP KEY ENTRY KEY CODE

COMMENTS

STEP KEY ENTRY KEY CODE

COMMENTS

001 *LBLα 21 16 11
 002 DSP2 -63 02
 003 CLRG 16-53
 004 CLX -51
 005 RTN 24
 006 *LBLA 21 11
 007 ST07 35 07
 008 ENT↑ -21
 009 FRC 16 44
 010 ST02 35 02
 011 - -45
 012 ST03 35 03
 013 RCL7 36 07
 014 RTN 24
 015 *LBLB 21 12
 016 ST07 35 07
 017 ST+1 35-55 01
 018 RCL2 36 02
 019 × -35
 020 RCL3 36 03
 021 X*Y -41
 022 →R 44
 023 ST+4 35-55 04
 024 X*Y -41
 025 ST+5 35-55 05
 026 RCL7 36 07
 027 RTN 24
 028 *LBLC 21 13
 029 RCL5 36 05
 030 RCL1 36 01
 031 ÷ -24
 032 RCL4 36 04
 033 RCL1 36 01
 034 ÷ -24
 035 →P 34
 036 ST06 35 06
 037 R↓ -31
 038 ST07 35 07
 039 ENT↑ -21
 040 CLX -51
 041 X>Y? 16-34
 042 GSBc 23 16 13
 043 + -55
 044 . -62
 045 5 05
 046 + -55
 047 INT 16 34
 048 RCL6 36 06
 049 + -55
 050 RTN 24
 051 *LBLc 21 16 13
 052 CLX -51
 053 3 03
 054 6 06
 055 0 00
 056 RTN 24

060

070

080

090

100

110

FLAGS

SET STATUS

0	FLAGS		TRIG		DISP
	ON	OFF			
1	<input type="checkbox"/>	<input checked="" type="checkbox"/>	DEG <input checked="" type="checkbox"/>	SCI <input type="checkbox"/>	FIX <input checked="" type="checkbox"/>
2	<input type="checkbox"/>	<input checked="" type="checkbox"/>	GRAD <input type="checkbox"/>	ENG <input type="checkbox"/>	
3	<input type="checkbox"/>	<input checked="" type="checkbox"/>	RAD <input type="checkbox"/>		n 2

REGISTERS

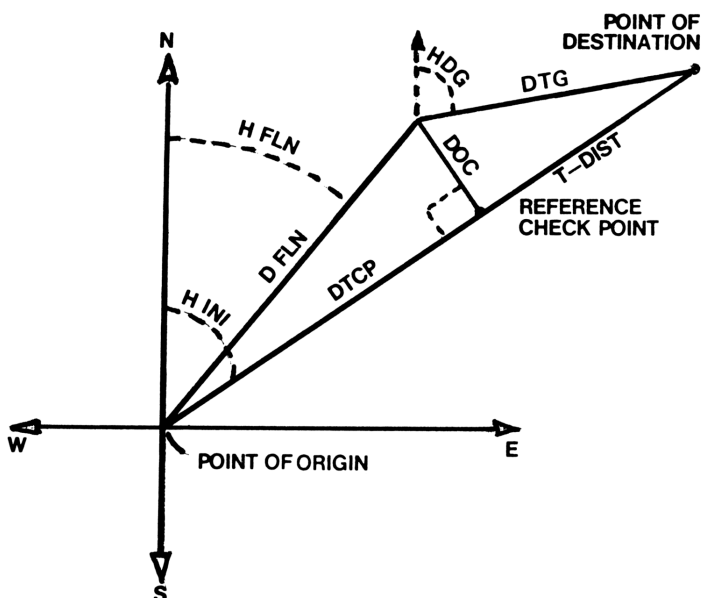
0	1 Sum D	2 1/100	3 WIND°	4 E _x	5 E _y	6 Ave 1/100	7 USED	8	9
S0	S1	S2	S3	S4	S5	S6	S7	S8	S9
A	B	C	D	E	I				

Program Description I

Program Title	Course Correction		
Contributor's Name	Hewlett-Packard		
Address	1000 N.E. Circle Blvd.		
City	Corvallis	State	Oregon
		Zip Code	97330

Program Description, Equations, Variables

The program calculates the new corrected heading and the distance to destination for an aircraft which has strayed a known distance off course.



Operating Limits and Warnings

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Program Description I

Program Title _____

Contributor's Name _____

Address _____

City _____

State _____

Zip Code _____

Program Description, Equations, Variables

The following inputs are used in calculations.

DOC = Distance off course (this is input as a positive quantity if you are left of course and as a negative quantity if you are to the right of course);

T DIST = Total distance from the point of origin to the point of destination;

DTCP = Distance to checkpoint from point of origin;

D FLN = Distance actually flown from origin to point of course correction calculation. This value may be used instead of DTCP. When it is used it is input as a negative quantity;

H INI = The initial heading that should have been flown to arrive at the point of destination;

H FLN = The heading actually flown to arrive at the point of calculation for course correction. It may be used instead of H INI. If it is, it is input as a negative value;

The outputs of calculation are:

HDG = The new heading to be flown to arrive at the point of destination;

Operating Limits and Warnings

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Program Description I

Program Title

Contributor's Name

Address

CityStateZip Code

Program Description, Equations, Variables

DTG = The distance to go from the point of calculation;

$$DTCP = \sqrt{(-DF)^2 - (DOC)^2}$$
$$DTG = \sqrt{(DTCP - T \text{ DIST})^2 + (DOC)^2}$$
$$HDG = \sin^{-1} \left[\frac{DOC}{DTG} \right] + H \text{ INI}$$

Operating Limits and Warnings

Limits and Warnings

This program assumes a flat earth. Large distances or calculations near the poles will yield inaccurate results.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Program Description II

[illegible][illegible]

Reference(s)

— This program is a direct translation of a program from the HP-65
— Aviation Pac. —

47

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	*LBLA	21 16 11		057	ST08	35 08	
002	CLRG	16-53		058	3	03	
003	CLX	-51		059	6	06	
004	RTN	24		060	0	00	
005	*LBLA	21 11		061	X≤Y?	16-35	
006	ST01	35 01		062	GSe	23 16 15	
007	RTN	24		063	0	00	
008	*LBLB	21 12		064	RCL8	36 08	
009	ST04	35 04		065	X≤Y?	16-35	
010	RTN	24		066	GSe	23 16 14	
011	*LBLC	21 13		067	0	00	
012	ST02	35 02		068	+	-55	
013	RTN	24		069	ST08	35 08	
014	*LBLD	21 14		070	RTN	24	
015	ST03	35 03		071	*LBLE	21 15	
016	RTN	24		072	RCL6	36 06	
017	*LBLE	21 15		073	RTN	24	
018	RCL2	36 02		074	*LBLe	21 16 15	
019	0	00		075	-	-45	
020	X≤Y?	16-35		076	ST08	35 08	
021	GT03	22 03		077	RTN	24	
022	RCL2	36 02		078	*LBLd	21 16 14	
023	X²	53		079	3	03	
024	RCL1	36 01		080	6	06	
025	X²	53		081	0	00	
026	-	-45		082	+	-55	
027	JX	54		083	RTN	24	
028	ENT↑	-21					
029	*LBL3	21 03					
030	R↓	-31					
031	ST05	35 05					
032	RCL4	36 04					
033	-	-45					
034	X²	53					
035	RCL1	36 01					
036	X²	53					
037	+	-55					
038	JX	54					
039	ST06	35 06					
040	RCL1	36 01					
041	X≠Y	-41					
042	=	-24					
043	SIN⁻¹	16 41					
044	ST07	35 07					
045	RCL3	36 03					
046	X>0?	16-44					
047	GT01	22 01					
048	CHS	-22					
049	RCL1	36 01					
050	RCL5	36 05					
051	÷	-24					
052	TAN⁻¹	16 43					
053	+	-55					
054	*LBL1	21 01					
055	RCL7	36 07					
056	+	-55					

REGISTERS

0	1	2-D FLV	3-H FLV	4	5	6	7	8	9
	DOC	OR DTCP	OR HIVE	T DIST	DTCP	DTG	CORRELATION	HOG	
S0	S1	S2	S3	S4	S5	S6	S7	S8	S9
A	B	C	D	E	I				

Program Description I

Program Title Time of Sunrise and/or Sunset

Contributor's Name Hewlett-Packard

Address 1000 N.E. Circle Blvd.

City Corvallis

State Oregon

Zip Code 97330

Program Description, Equations, Variables

Sunrise is computed from

$$S = [\theta_0 - \cos^{-1} (-\tan\phi_s \tan\phi_0)] / 15 - E + 12 \quad (1)$$

where

θ_0 = observer's longitude

ϕ_0 = observer's latitude

ϕ_s = subsolar latitude (declination of sun)

E = equation of time

ϕ_s and E are approximated by

$$\phi_s \doteq -23.5 \cos(t + 10) \quad (2)$$

$$E \doteq 0.123 \cos(t + 87) - \frac{1}{6} \sin(2t + 20) \quad (3)$$

$$t \doteq 0.988 (D - 1 + 30.3 (m - 1)) \quad (9)$$

where D and m are day and month respectively.

NOTE: Equation (1) computes the time at which the middle of the sun is on the horizon. Equation (1) does not account for atmospheric refractions. Refraction causes the sun to rise earlier than the value given by equation (1).

Operating Limits and Warnings

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Program Description I

Program Title _____

Contributor's Name _____

Address _____

City _____

State _____

Zip Code _____

Program Description, Equations, Variables

Sunset is computed from

$$S = [\theta_0 + \cos^{-1}(-\tan\phi_s \tan\phi_0)]/15 - E + 12 \quad (1)$$

where:

θ_0 = observer's longitude

ϕ_0 = observer's latitude

ϕ_s = subsolar latitude (declination of sun)

E = equation of time

ϕ_s and E are approximated by

$$\phi_s \doteq -23.5 \cos(t + 10)$$

$$E \doteq 0.123 \cos(t + 87) - \frac{1}{6} \sin(2t + 29)$$

$$t \doteq 0.988(D - 1 + 30.3(m - 1))$$

where D and m are day and month respectively.

NOTE: Equation (1) computes the time at which the middle of the sun is on the horizon. Equation (1) does not account for atmospheric refractions. Refraction causes the sun to *set later* than the value given by equation (1).

Operating Limits and Warnings

Limits and Warnings

The approximate values of ϕ_s and E cause s to exhibit a maximum error of +4.7 minutes and -0.6 minutes at 45° north latitude, based on 1973 ephemeris data. Refraction and secular changes in the ephemeris can result in errors as large as +8 minutes from observed data at 45° north. Errors decrease as latitudes approach 0°. Large errors exist above 65°.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Program Description II

[illegible]

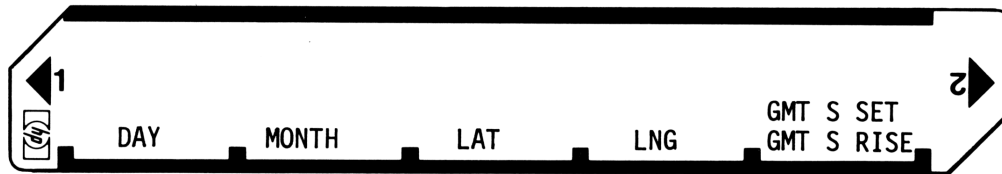
Sample Problem(s)
<p>Sample Problems</p> <p>What time does the sun rise in San Francisco ($37^{\circ} 37' N$, $122^{\circ} 23' W$) on Christmas Day? What time does the sun rise on June 25?</p>
Solution(s)
<p>Solutions</p> <p>15:27 GMT (07:27 AM Pacific Standard Time) 12:53 GMT (05:53 AM Pacific Daylight Time)</p> <p>Keystrokes</p> <p>25 A 12 B 37.37 C 122.23 D</p> <p>E</p> <p>6 B E</p>
<p>See Displayed</p> <p>15.27</p> <p>12.53</p>

Reference(s) _____

_____ This program is a direct translation of a program from the HP-65 _____

_____ Aviation Pac. _____

User Instructions

[illegible]

97 Program Listing I

STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	*LBLA	21 11		057	2	02	
002	ST01	35 01		058	3	03	
003	RTN	24		059	.	-62	
004	*LBLB	21 12		060	5	05	
005	ST02	35 02		061	x	-35	
006	RTN	24		062	TAN	43	
007	*LBLC	21 13		063	RCL3	36 03	
008	ST03	35 03		064	HMS+	16 36	
009	RTN	24		065	TAN	43	
010	*LBLD	21 14		066	x	-35	
011	ST04	35 04		067	COS-	16 42	
012	RTN	24		068	F2?	16 23 02	
013	*LBLE	21 15		069	GT0c	22 16 13	
014	3	03		070	CHS	-22	
015	0	00		071	RCL4	36 04	
016	.	-62		072	HMS+	16 36	
017	3	03		073	+	-55	
018	RCL2	36 02		074	1	01	
019	1	01		075	5	05	
020	-	-45		076	÷	-24	
021	x	-35		077	+	-55	
022	RCL1	36 01		078	1	01	
023	+	-55		079	2	02	
024	1	01		080	+	-55	
025	-	-45		081	ENT↑	-21	
026	.	-62		082	CLX	-51	
027	9	09		083	X>Y?	16-34	
028	8	08		084	GSAa	23 16 11	
029	8	08		085	+	-55	
030	x	-35		086	+HMS	16 35	
031	ST05	35 05		087	RTN	24	
032	8	08		088	*LBLc	21 16 15	
033	7	07		089	SF2	16 21 02	
034	+	-55		090	GT0E	22 15	
035	COS	42		091	*LBLc	21 16 13	
036	.	-62		092	RCL4	36 04	
037	1	01		093	HMS+	16 36	
038	2	02		094	+	-55	
039	3	03		095	1	01	
040	x	-35		096	5	05	
041	RCL5	36 05		097	÷	-24	
042	ENT↑	-21		098	+	-55	
043	+	-55		099	1	01	
044	2	02		100	2	02	
045	0	00		101	+	-55	
046	+	-55		102	2	02	
047	SIN	41		103	4	04	
048	6	06		104	X>Y?	16-34	
049	÷	-24		105	GSAa	23 16 12	
050	-	-45		106	-	-45	
051	CHS	-22		107	+HMS	16 35	
052	RCL5	36 05		108	RTN	24	
053	1	01		109	*LBLa	21 16 11	
054	0	00		110	2	02	
055	+	-55		111	4	04	
056	COS	42		112	RTN	24	

REGISTERS

0	1 DAY	2 MONTH	3 LAT	4 LONG	5 ±	6	7	8	9
S0	S1	S2	S3	S4	S5	S6	S7	S8	S9
A	B	C	D	E	I				

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[illegible]

Program Description I

Program Title	Azimuth of Sunrise and Sunset		
Contributor's Name	Hewlett-Packard		
Address	1000 N.E. Circle Blvd.		
City	Corvallis	State	Oregon
		Zip Code	97330

Program Description, Equations, Variables

This program computes the true heading (azimuth) of the sun as it rises or sets. Input data are day of the month, month of the year and latitude.

The azimuth of the sun is given by

$$Az = \cos^{-1} \frac{\sin \phi_s}{\cos \phi_o}$$

ϕ_s is the latitude of the subsolar point

ϕ_o is the latitude of the observer

ϕ_s is approximated by

$$\phi_s = 0.5 - 23.5 \cos(0.986 \text{ day} + 9.66) \text{ where day is the day of the year.}$$

Operating Limits and Warnings

The approximations used in this program limit the overall accuracy to $\approx 1\%$.

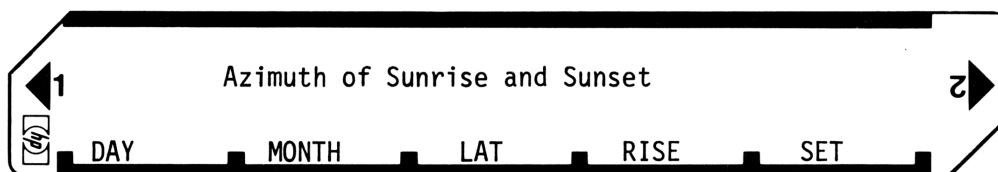
Significant errors can occur at or above the arctic circles and their respective poles during certain times of the year.

This program has been verified only with respect to the numerical example given in *Program Description II*. User accepts and uses this program material AT HIS OWN RISK, in reliance solely upon his own inspection of the program material and without reliance upon any representation or description concerning the program material.

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Reference(s) _____

_____ This program is a direct translation of a program from the HP-65
_____ Aviation Pac. _____

[illegible]

97 Program Listing I

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STEP	KEY ENTRY	KEY CODE	COMMENTS	STEP	KEY ENTRY	KEY CODE	COMMENTS
001	*LBLA	21 11		057	HMS→	16 36	
002	ST01	35 01		058	COS	42	
003	RTN	24		059	÷	-24	
004	*LBLB	21 12		060	COS→	16 42	
005	ST02	35 02		061	3	03	
006	RTN	24		062	6	06	
007	*LBLC	21 13		063	0	00	
008	ST03	35 03		064	X→Y	-41	
009	RTN	24		065	F2?	16 23 02	
010	*LBLD	21 14		066	-	-45	
011	RCL2	36 02		067	RTN	24	
012	.	-62		068	*LBLE	21 15	
013	4	04		069	SF2	16 21 02	
014	x	-35		070	GTOD	22 14	
015	2	02		071	*LBLd	21 16 14	
016	.	-62		072	CLX	-51	
017	3	03		073	ST08	35 08	
018	+	-55		074	RTN	24	
019	INT	16 34		075	R/S	51	
020	ST08	35 08					
021	2	02					
022	RCL2	36 02					
023	X→Y?	16-35					
024	GSBd	23 16 14					
025	RCL1	36 01					
026	RCL8	36 08					
027	-	-45					
028	RCL2	36 02					
029	1	01					
030	-	-45					
031	3	03					
032	1	01					
033	x	-35					
034	+	-55					
035	.	-62					
036	9	09					
037	8	08					
038	6	06					
039	x	-35					
040	9	09					
041	.	-62					
042	6	06					
043	6	06					
044	+	-55					
045	COS	42					
046	2	02					
047	3	03					
048	.	-62					
049	5	05					
050	x	-35					
051	CHS	-22					
052	.	-62					
053	5	05					
054	+	-55					
055	SIN	41					
056	RCL3	36 03					

REGISTERS									
0	1 DAY	2 MONTH	3 LAT	4	5	6	7	8 0.4m+2.3	9
S0	S1	S2	S3	S4	S5	S6	S7	S8	S9
A	B	C	D	E	I				

FLAGS		SET STATUS		
		FLAGS	TRIG	DISP
0	ON OFF	DEG <input checked="" type="checkbox"/>	FIX <input checked="" type="checkbox"/>	
1	<input type="checkbox"/>	GRAD <input type="checkbox"/>	SCI <input type="checkbox"/>	
2	<input checked="" type="checkbox"/>	RAD <input type="checkbox"/>	ENG <input type="checkbox"/>	
3	<input checked="" type="checkbox"/>		n 2	

NOTES

Hewlett-Packard Software

In terms of power and flexibility, the problem-solving potential of the Hewlett-Packard line of fully programmable calculators is nearly limitless. And in order to see the practical side of this potential, we have several different types of software to help save you time and programming effort. Every one of our software solutions has been carefully selected to effectively increase your problem-solving potential. Chances are, we already have the solutions you're looking for.

Application Pacs

To increase the versatility of your fully programmable Hewlett-Packard calculator, HP has an extensive library of "Application Pacs". These programs transform your HP-67 and HP-97 into specialized calculators in seconds. Each program in a pac is fully documented with commented program listing, allowing the adoption of programming techniques useful to each application area. The pacs contain 20 or more programs in the form of prerecorded cards, a detailed manual, and a program card holder. Every Application Pac has been designed to extend the capabilities of our fully programmable models to increase your problem-solving potential.

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Mathematics
Electrical Engineering
Business Decisions
Clinical Lab and Nuclear Medicine

Mechanical Engineering
Surveying
Civil Engineering
Navigation

Users' Library

The main objective of our Users' Library is dedicated to making selected program solutions contributed by our HP-67 and HP-97 users available to you. By subscribing to our Users' Library, you'll have at your fingertips, literally hundreds of different programs. No longer will you have to: research the application; program the solution; debug the program; or complete the documentation. Simply key your program to obtain your solution. In addition, programs from the library may be used as a source of programming techniques in your application area.

A one-year subscription to the Library costs \$9.00. You receive: a catalog of contributed programs; catalog updates; and coupons for three programs of your choice (a \$9.00 value).

Users' Library Solutions Books

Hewlett-Packard recently added a unique problem-solving contribution to its existing software line. The new series of software solutions are a collection of programs provided by our programmable calculator users. Hewlett-Packard has currently accepted over 6,000 programs for our Users' Libraries. The best of these programs have been compiled into 40 Library Solutions Books covering 39 application areas (including two game books).

Each of the Books, containing up to 15 programs without cards, is priced at \$10.00, a savings of up to \$35.00 over single copy cost.

The Users' Library Solutions Books will compliment our other applications of software and provide you with a valuable new tool for program solutions.

Options/Technical Stock Analysis
Portfolio Management/Bonds & Notes
Real Estate Investment
Taxes
Home Construction Estimating
Marketing/Sales
Home Management
Small Business
Antennas
Butterworth and Chebyshev Filters
Thermal and Transport Sciences
EE (Lab)
Industrial Engineering
Aeronautical Engineering
Control Systems
Beams and Columns
High-Level Math
Test Statistics
Geometry
Reliability/QA

Medical Practitioner
Anesthesia
Cardiac
Pulmonary
Chemistry
Optics
Physics
Earth Sciences
Energy Conservation
Space Science
Biology
Games
Games of Chance
Aircraft Operation
Aviation
Calendars
Photo Dark Room
COGO-Surveying
Astrology
Forestry

AVIGATION

This book contains programs dealing with great circle and rhumb line calculations, dead reckoning, position by one or two VOR's and time and azimuth of sunrise or sunset.

GREAT CIRCLE PLOTTING

RHUMB LINE NAVIGATION

GREAT CIRCLE NAVIGATION

POSITION GIVEN HEADING, SPEED AND TIME

LINE OF SIGHT DISTANCE

POSITION AND/OR NAVIGATION BY TWO VOR'S

POSITION BY ONE VOR

DME SPEED CORRECTION

AVERAGE WIND VECTOR

COURSE CORRECTION

TIME OF SUNRISE AND SUNSET

AZIMUTH OF SUNRISE AND SUNSET



Program Listing I

17

S

COMMENTS

STEP

KEY ENTRY

KEY CODE

COMMENTS

001 *LBLA 21 11
 002 HMS+ 16 36
 003 RCL4 36 04
 004 ST02 35 02
 005 X=Y -41
 006 ST04 35 04
 007 RTN 24
 008 *LBLB 21 12
 009 ST05 35 05
 010 RTN 24
 011 *LBLC 21 13
 012 ST06 35 06
 013 RTN 24
 014 *LBLD 21 14
 015 HMS+ 16 36
 016 RCL6 36 06
 017 X -35
 018 6 06
 019 0 00
 020 ÷ -24
 021 ST07 35 07
 022 RCL5 36 05
 023 COS 42
 024 X -35
 025 RCL2 36 02
 026 + -55
 027 ST01 35 01
 028 GSBF 23 15
 029 RCL2 36 02
 030 GSBF 23 15
 031 X=Y? 16-33
 032 GT02 22 02
 033 - -45
 034 RCL5 36 05
 035 TAN 42
 036 X -35
 037 P1 16-24
 038 ÷ -24
 039 1 01
 040 8 08
 041 0 00
 042 X -35
 043 *LBL1 21 01
 044 CHS -22
 045 RCL4 36 04
 046 + -55
 047 1 01
 048 +R 44
 049 +P 34
 050 R↓ -31
 051 ST03 35 03
 052 RCL1 36 01
 053 +HMS 16 35
 054 RTN 24
 055 *LBL2 21 02
 056 RCL7 36 07

057 RCL5 36 05
 058 SIN 41
 059 X -35
 060 RCL2 36 02
 061 COS 42
 062 ÷ -24
 063 GT01 22 01
 064 *LBLE 21 14
 065 RCL3 36 03
 066 +HMS 16 35
 067 RTN 24
 068 *LBLE 21 15
 069 2 02
 070 ÷ -24
 071 4 04
 072 5 05
 073 + -55
 074 TAN 42
 075 LN 32
 076 RTN 24
 077 R/S 51

L1

080

090

100

110

FLAGS

SET STATUS

0	FLAGS			SET STATUS		
	ON OFF			TRIG	DISP	
1	0	<input type="checkbox"/>	<input checked="" type="checkbox"/>	DEG <input checked="" type="checkbox"/>	FIX <input checked="" type="checkbox"/>	
2	1	<input type="checkbox"/>	<input checked="" type="checkbox"/>	GRAD <input type="checkbox"/>	SCI <input type="checkbox"/>	
3	2	<input type="checkbox"/>	<input checked="" type="checkbox"/>	RAD <input type="checkbox"/>	ENG <input type="checkbox"/>	
	3	<input type="checkbox"/>	<input checked="" type="checkbox"/>			

REGISTERS

16 D	4 LNG S	5 HDG	6 SPEED	7 DIST	8	9
	S4	S5	S6	S7	S8	S9

0
 S0

A	B	C	D	E	I
---	---	---	---	---	---

Program Comments

This form is your vehicle for commenting on programs obtained from the Users' Library. Your comments will be reviewed by the Library and when appropriate, the program contributor shall be contacted to initiate revisions. Please complete this form and mail to:

Hewlett Packard Company
Attention: Users' Library
1000 N.E. Circle Blvd
Corvallis, Oregon 97330

Report on Program Number

0,0,6,1,1,D

Title: TIME OF SUNRISE &/OR SUNSET - USERS LIBRARY SOLUTIONS - AVIGATION

Commenter's Name: DAVID G. JONES

Address: NEWMONT PROPRIETARY LIMITED, 535 BOURKE STREET,

MELBOURNE, VICTORIA

Street

AUSTRALIA

3000

City

State

Zip Code

Comments:

THERE ARE TWO (2) ERRORS IN THE PROGRAM LISTING.

(a) STEP 107 READS HMS → 16 36

IT SHOULD READ → HMS 16 35

(b) STEP 111 IN SUBROUTINE "A" SHOULD BE FOLLOWED BY

STEP 112 + -55 (THIS IS AN EXTRA - AND NECESSARY - STEP)

113 RTN 24

114 *LBL 21 16 12

115 ENT ↑ -21

116 - -45

117 RTN 24

RECEIVED

APR 18 1980

USERS LIBRARY

THESE CORRECTIONS THEN MAKE IT POSSIBLE FOR US
"DOWN UNDER" IN THE SOUTHERN HEMISPHERE TO TELL LIGHT
FROM DARKNESS, WITHOUT UPSETTING THOSE OF YOU IN
NORTHERN CLIMES!